

Enclosures PwrPak7-E2™



OEM7® SPAN® GNSS+INS ENCLOSURE WITH IMPROVED PERFORMANCE AND HIGHER DATA RATES



SPAN: WORLD LEADING GNSS+INS TECHNOLOGY

Synchronous Position, Attitude and Navigation (SPAN) technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and Inertial Navigation System (INS). The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

SPAN ENABLED MEMS RECEIVER

The PwrPak7-E2 contains an Epson G370N MEMS IMU to deliver world class NovAtel® SPAN technology in an integrated, single box solution. Built on top of the reputable PwrPak7 family, with a higher performance Epson IMU, it provides seamless positioning, quick alignment and excellent performance. This product is commercially exportable and provides an excellent midrange price/performance/size GNSS+INS solution.

FUTURE PROOFED SCALABILITY

Capable of tracking all present and upcoming GNSS constellations and satellite signals, the PwrPak7-E2 is a robust, high precision receiver that is software upgradeable in the field to provide the custom performance required for your application demands.

The PwrPak7-E2 has a powerful OEM7 GNSS engine, integrated MEMS IMU, built in Wi-Fi, on board NTRIP client and server support, and 16 GB of internal storage. It also has enhanced connection options including serial, USB, CAN and Ethernet.

PRECISE THINKING MAKES IT POSSIBLE

Developed for efficient and rapid integration, our GNSS products have set the standard in quality and performance for over 20 years. State-of-the-art, lean manufacturing facilities in our North American headquarters produce the industry's most extensive line of OEM receivers, antennas and subsystems. All of our products are backed by a team of highly skilled design and customer support engineers, ready to answer your integration questions.

FEATURES

- + SPAN enabled enclosure featuring NovAtel's tightly coupled GNSS+INS engine
- + 555 channel, all-constellation, multi-frequency positioning solution
- + TerraStar® correction services supported over multi-channel L-Band and IP connections
- + Commercially exportable IMU
- + INS data rates up to 200 Hz
- + Multiple communication interfaces for easy integration and installation
- + Built-in Wi-Fi support
- + 16 GB of internal storage
- + Can be paired with an external receiver to support ALIGN® GNSS azimuth aiding for low dynamic applications

If you require more information about our enclosures, visit www.novatel.com/products/span-gnss-inertial-systems/span-combined-systems/

PwrPak7-E2™



PERFORMANCE¹

Channel Configuration

555 Channels

Signal Tracking

GPS L1 C/A, L1C, L2C, L2P, L5

GLONASS² L1 C/A, L2 C/A, L2P, L3, L5

Galileo³ E1, E5 AltBOC, E5a, E5b, E6

BeiDou B1I, B1C, B2I, B2a, B3I

QZSS L1 C/A, L1C, L2C, L5, L6

NavIC (IRNSS) L5

SBAS L1, L5

L-Band up to 5 channels

GNSS Horizontal Position

Accuracy (RMS)

Single point L1 1.5 m

Single point L1/L2 1.2 m

SBAS⁴ 60 cm

DGPS 40 cm

TerraStar-L™⁵ 40 cm

TerraStar-C PRO™⁵ 2.5 cm

TerraStar-X™⁵ 2 cm

RTK 1 cm + 1 ppm

Initialization time <10 s

Initialization reliability >99.9%

Maximum Data Rate

GNSS Measurements up to 20 Hz

GNSS Position up to 20 Hz

INS Position/Attitude up to 200 Hz

IMU Raw Data Rate 200 Hz

Time to First Fix

Cold start⁶ <39 s

Hot start⁷ <20 s

Time Accuracy⁸ 20 ns RMS

Velocity Limit⁹ 515 m/s

IMU PERFORMANCE¹⁰

Gyroscope Performance

Input range ±450 deg/s

Rate bias stability 0.8 deg/hr

Angular random walk

0.06 deg/√hr

Accelerometer Performance

Range ±10 g

Bias stability 0.01 mg

Velocity random walk

0.025 m/s/√hr

COMMUNICATION PORTS

1 RS-232 up to 460,800 bps

2 RS-232/RS-422 selectable

up to 460,800 bps

1 USB 2.0 (device) HS

1 USB 2.0 (host) HS

1 Ethernet 10/100 Mbps

1 CAN Bus 1 Mbps

1 Wi-Fi

3 Event inputs

3 Event outputs

1 Pulse Per Second output

1 Quadrature Wheel Sensor input

PHYSICAL AND ELECTRICAL

Dimensions 147 x 125 x 55 mm

Weight 560 g

Power

Input voltage +9 to +36 VDC

Power consumption¹¹ 3.4 W

Antenna LNA Power Output

Output voltage 5 VDC ±5%

Maximum current 200 mA

Connectors

Antenna TNC

USB device Micro A/B

USB host Micro A/B

Serial, CAN, Event I/O

DSUB HD26

Ethernet RJ45

Data Logging Push button

Power SAL M12, 5 pin, male

Status LEDs

Power

GNSS

INS

Data Logging

USB

ENVIRONMENTAL

Temperature

Operating -40°C to +75°C

Storage -40°C to +85°C

Humidity 95% non-condensing

Ingress Protection Rating

IP67

Random Vibration

MIL-STD-810G(CH1),

Method 514.7 – Profiles:

» Rail CAT 11 – 0.5 g RMS

» Composite Wheeled Vehicle

CAT 4 – 2.24 g RMS

» Aircraft Propeller

CAT 13 – 4.5 g RMS

Acceleration (operating)

MIL-STD-810G(CH1),

Method 513.7, Procedure II (16g)

Bump

IEC 60068-2-27 (25 g)

Shock (operating)¹²

MIL-STD-810G(CH1),

Method 516.7, Procedure 1,

40 g 11 ms terminal sawtooth

COMPLIANCE

FCC, ISED, CE and

Global Type Approvals

INCLUDED ACCESSORIES

- Power cable
- USB cable
- DSUB HD26 to DB9 RS-232 cable

OPTIONAL ACCESSORIES

- Full breakout cable for DSUB HD26 connector
- DSUB HD26 to M12 IMU cable
- RJ45 Ethernet cable
- VEXXIS® GNSS-500 and GNSS-800 series antennas
- Compact GNSS antennas
- GrafNav/GrafNet®
- Inertial Explorer®
- NovAtel Connect

For the most recent details of this product:

www.novatel.com/products/span-gnss-inertial-systems/span-combined-systems/pwrpak7-e2/

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Version 1

Specifications subject to change without notice.

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PERFORMANCE DURING GNSS OUTAGES¹

Outage Duration	Positioning Mode	POSITION ACCURACY (M) RMS		VELOCITY ACCURACY (M/S) RMS		ATTITUDE ACCURACY (DEGREES) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK ¹³	0.02	0.03	0.015	0.010	0.013	0.013	0.070
	SP	1.00	0.60	0.015	0.010	0.013	0.013	0.070
	PP ¹⁴	0.01	0.02	0.010	0.010	0.005	0.005	0.011
10 s	RTK ¹³	0.15	0.10	0.040	0.020	0.022	0.022	0.085
	SP	1.15	0.70	0.040	0.020	0.022	0.022	0.085
	PP ¹⁴	0.02	0.02	0.010	0.014	0.005	0.005	0.011
60 s	RTK ¹³	5.00	1.00	0.220	0.035	0.035	0.035	0.120
	SP	6.00	1.60	0.220	0.035	0.035	0.035	0.120
	PP ¹⁴	0.17	0.06	0.013	0.015	0.005	0.005	0.013

¹ Typical values. Performance specifications subject to GNSS system characteristics, Signal-In-Space (SIS) operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference sources.

² Hardware ready for L3 and L5.

³ E1bc and E6bc support only.

⁴ GPS only.

⁵ Requires a subscription to a TerraStar data service. Subscriptions available from NovAtel.

⁶ Typical value. No almanac or ephemerides and no approximate position or time.

⁷ Typical value. Almanac and recent ephemerides saved and approximate position and time entered.

⁸ Time accuracy does not include biases due to RF or antenna delay.

⁹ Export licensing restricts operation to a maximum of 515 meters per second, message output impacted above 500 m/s.

¹⁰ Supplied by IMU manufacturer.

¹¹ Typical value. Consult the OEM7 User Documentation for power supply considerations.

¹² GNSS only. IMU measurements may not be valid.

¹³ 1 ppm should be added to all position values to account for additional error due to baseline length.

¹⁴ Post-processing results using Inertial Explorer software. The survey data used to generate these statistics had frequent changes in azimuth.